

Introduction to Deep Learning (I2DL)

Exercise 6: Hyperparameter Tuning

Today's Outline

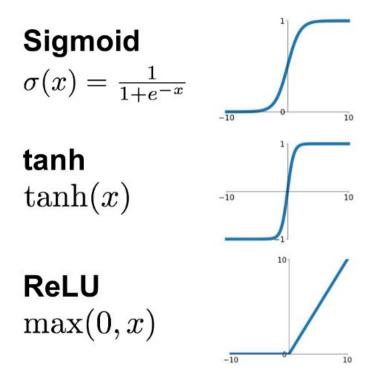
1. *Review Solution Exercise 5* Sigmoid Activation Function

2. Introduction Exercise 6 Hyperparameter Tuning

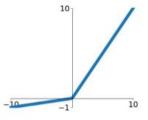


Activation functions

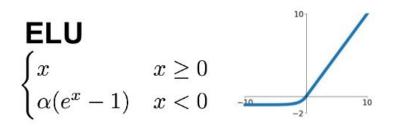
Activation functions



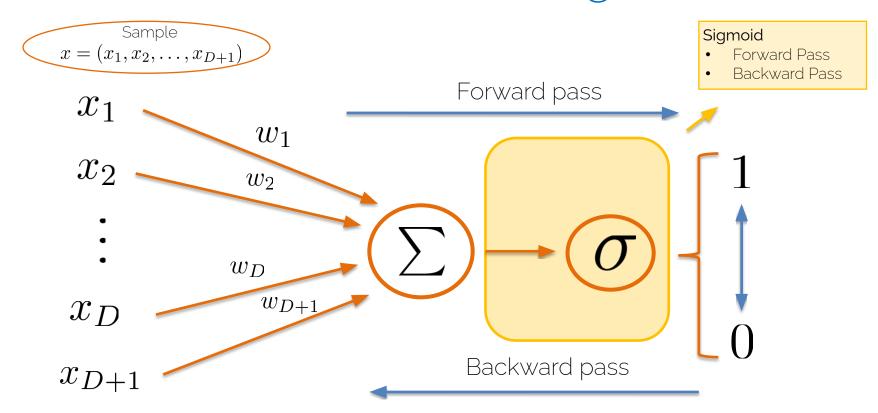
Leaky ReLU $\max(0.1x, x)$



 $\begin{array}{l} \textbf{Maxout} \\ \max(w_1^T x + b_1, w_2^T x + b_2) \end{array}$



Activation function: Sigmoid



Sigmoid: Forward pass

• Definition of the Sigmoid function:

$$\sigma: \mathbb{R} \to \mathbb{R}, \sigma(x) = \frac{1}{1 + e^{-x}}$$

• Derivative of the sigmoid function:

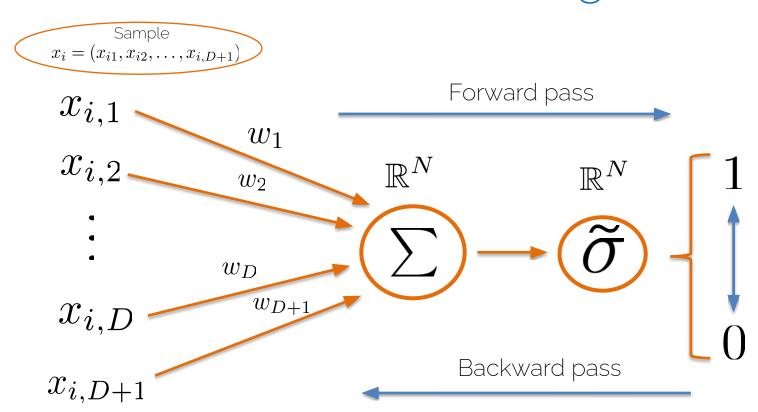
$$\frac{\partial \sigma(x)}{\partial x} = \sigma(x) \cdot (1 - \sigma(x))$$

• Application of the Sigmoid function in higher dimension:

$$\tilde{\sigma}: \mathbb{R}^N \to \mathbb{R}^N, \tilde{\sigma}(x) = \begin{pmatrix} \sigma(x_1) \\ \sigma(x_2) \\ \vdots \\ \sigma(x_N) \end{pmatrix}$$

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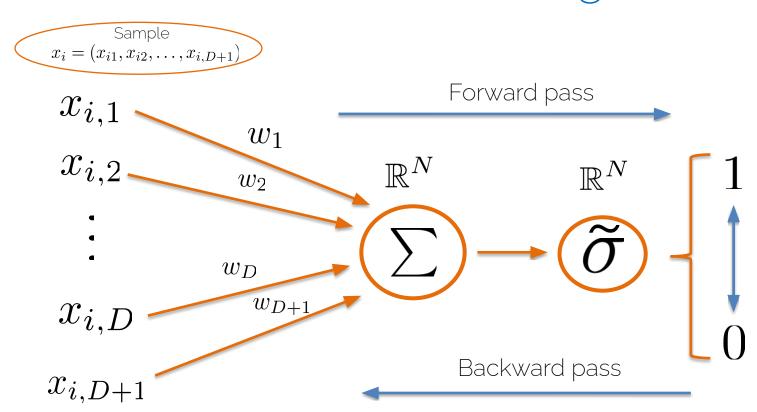
Activation function: Sigmoid



Sigmoid: Forward pass

```
def forward(self, x):
  :param x: Inputs, of any shape.
  :return out: Outputs, of the same shape as x.
  :return cache: Cache, stored for backward computation, of the same shape as x.
   .....
  shape = x.shape
  out, cache = np.zeros(shape), np.zeros(shape)
   # TODO:
  # Implement the forward pass of Sigmoid activation function
   ****
  # out = np.ones like(x) / (np.ones like(x) +
  \sigma(x) =
  cache = out
   ################################
                       END OF YOUR CODE
   return out, cache
```

Activation function: Sigmoid



Sigmoid: Backward pass

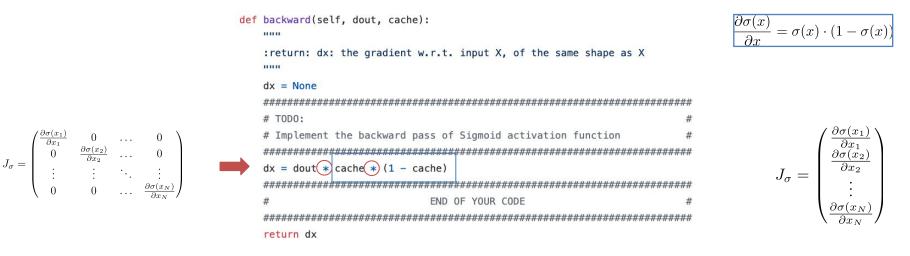
• The derivative of the sigmoid function is thus given a N x N - sized Jacobian matrix.

$$\tilde{\sigma} : \mathbb{R}^N \to \mathbb{R}^N, \tilde{\sigma}(x) = \begin{pmatrix} \sigma(x_1) \\ \sigma(x_2) \\ \vdots \\ \sigma(x_N) \end{pmatrix}$$

$$J_{\sigma}: \mathbb{R}^{N} \to \mathbb{R}^{N \times N}, J_{\sigma} = \begin{pmatrix} \frac{\partial \sigma(x_{1})}{\partial x_{1}} & \frac{\partial \sigma(x_{1})}{\partial x_{2}} & \dots & \frac{\partial \sigma(x_{1})}{\partial x_{N}} \\ \frac{\partial \sigma(x_{2})}{\partial x_{1}} & \frac{\partial \sigma(x_{2})}{\partial x_{2}} & \dots & \frac{\partial \sigma(x_{2})}{\partial x_{N}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial \sigma(x_{N})}{\partial x_{1}} & \frac{\partial \sigma(x_{N})}{\partial x_{2}} & \dots & \frac{\partial \sigma(x_{N})}{\partial x_{N}} \end{pmatrix} = \begin{pmatrix} \frac{\partial \sigma(x_{1})}{\partial x_{1}} & 0 & \dots & 0 \\ 0 & \frac{\partial \sigma(x_{2})}{\partial x_{2}} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \frac{\partial \sigma(x_{N})}{\partial x_{N}} \end{pmatrix}$$

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Sigmoid: Backward pass



On paper

- Cache is an N x 1 vector
- Derivative of Sigmoid is N x N matrix
- Multiplication is normal matrix multiplication

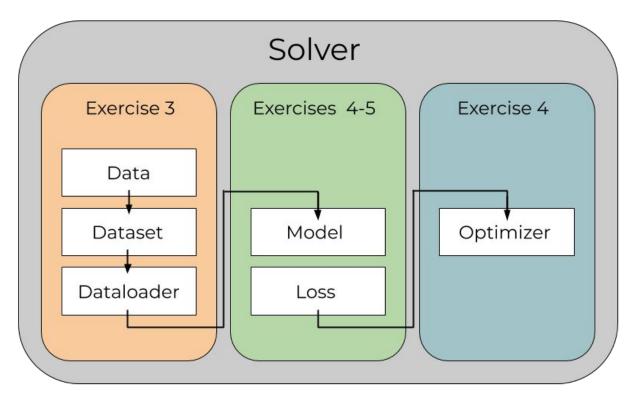
Numpy arrays

- Cache is a N x 1 vector
- Derivative of Sigmoid is given as N x 1 vector
- Multiplication: Numpy.multiply() which is componentwise multiplication



Exercise 6: Hyperparameter Tuning

Recap: Pillars of Deep Learning



Goal of exercise 6



Cifar10

Goal of exercise 6

- Use existing implementations
 - Reworked implementations of previous exercises
 - We will provide you with additional implementations of all required tools to run sample methods proposed in the lecture

 Learn about neural network debugging strategies and hyperparameter search



Leaderboard

- Your model's accuracy is all that counts!
 - At least 48% to pass the submission
 - There will be a leaderboard of all students!

Leaderboard

The leaderboard shows for each exercise the highest scoring submission from each user. Only valid submissions are displayed.

Exercise 1	Exercise 3	Exercise 4	Exercise 5	Exercise 6	Exercise 7	Exercise 8	Exercise 9	Exercise 10	Exercise 11
#			User				Scor	e	
1			a0008				100.0	00	
2			a0001				100.0	00	
3			a0003				100.0	00	
4			u0306				100.0	00	
5			u1540				100.0	00	

Previously: Dataset

```
class ImageFolderDataset(Dataset):
    """CIFAR-10 dataset class"""
    def init (self, transform=None, mode='train',
        limit files=None.
        split={'train': 0.6, 'val': 0.2, 'test': 0.2},
        *args, **kwargs): •••
   @staticmethod
   def find classes(directory): ....
   def select split(self, images, labels, mode): ***
   def make dataset(self, directory, class to idx, mode): •••
   def len (self): ....
   @staticmethod
    def load image as numpy(image path): ....
   def getitem (self, index): ....
```

```
# Create a train, validation and test dataset.
datasets = {}
for mode in ['train', 'val', 'test']:
    crt_dataset = ImageFolderDataset(
        mode=mode,
        root=cifar_root,
        download_url=download_url,
        transform=compose_transform,
        split={'train': 0.6, 'val': 0.2, 'test': 0.2}
    )
    datasets[mode] = crt_dataset
```

Previously: Data Loader

```
class DataLoader:
```

```
def __iter_(self): •••
```

```
def __len_(self): ...
```

```
# Create a dataloader for each split.
dataloaders = {}
for mode in ['train', 'val', 'test']:
    crt_dataloader = DataLoader(
        dataset=datasets[mode],
        batch_size=256,
        shuffle=True,
        drop_last=True,
        )
        dataloaders[mode] = crt_dataloader
```

Previously: Solver

```
class Solver(object):
    11.11.11
    A Solver encapsulates all the logic necessary for training classification
    or regression models.
    The Solver performs gradient descent using the given learning rate.
    11 11 11
    def init (self, model, train dataloader, val dataloader,
        loss func=CrossEntropyFromLogits(), learning rate=1e-3,
       optimizer=Adam, verbose=True, print every=1,
       lr decay = 1.0, **kwarqs): •••
    def reset(self): ....
    def step(self, X, y, validation=False): •••
    def train(self, epochs=100, patience = None): ...
    def get dataset accuracy(self, loader): •••
    def update best loss(self, val loss, train loss): ...
```

solver.train(epochs=epochs)

Previously: Classification Network

class ClassificationNet(Network):

A fully-connected classification neural network with configurable activation function, number of layers, number of classes, hidden size and regularization strength.

```
def __init__(self,
    activation=Sigmoid(), num_layer=2,
    input_size=3 * 32 * 32, hidden_size=100,
    std=le-3, num_classes=10, reg=0, **kwargs): ...
def forward(self, X): ...
def backward(self, dy): ...
def save_model(self, dy): ...
def get_dataset_prediction(self, loader): ...
```


X is a batch of training features
X.shape = (batch_size, features_size)
y_out = model.forward(X)

dout is the gradient of the loss function
w.r.t the output of the network.
dout.shape = (batch_size,)
model.backward(dout)

Previously: Binary Cross Entropy Loss

•
BCE
$$(\hat{y}, y) = \frac{1}{N} \sum_{i=1}^{N} \left[-y_i \log(\hat{y}_i) - (1 - y_i) \log(1 - \hat{y}_i) \right]$$

Where

- N is the number of samples
 - Λ
- y_i is the network's prediction for sample i
- y_i is the ground truth label (0 or 1)

New: Multiclass Cross Entropy Loss

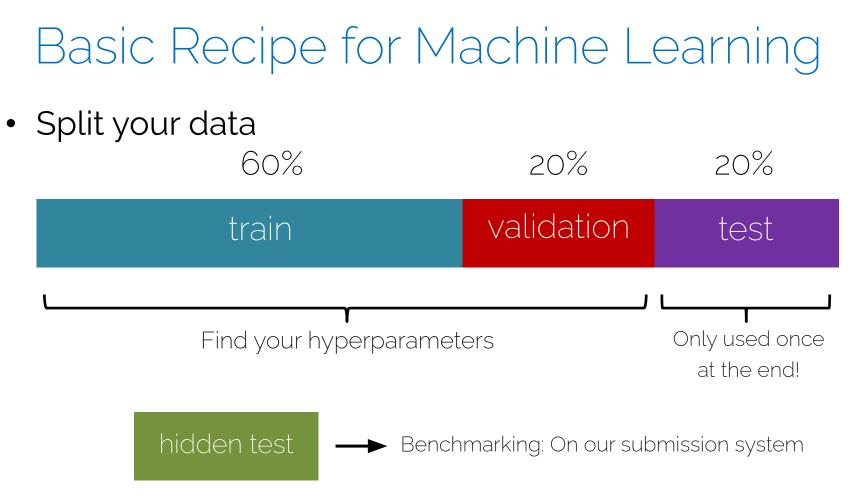
$$\stackrel{\bullet}{CE}\left(\hat{y},y\right) = \frac{1}{N} \sum_{i=1}^{N} \sum_{k=1}^{C} \left[-y_{ik} \log\left(\hat{y}_{ik}\right)\right]$$

Where

N is the number of samples

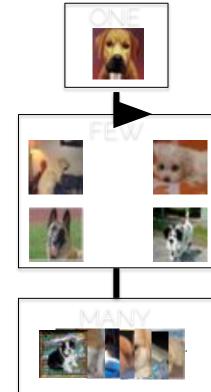
We implemented this for you! More on this topic in the next lecture.

- y_{ik} is the network's predicted probability for the kth class when given the sample i
- **y**_{*ik*} is the ground truth label which is either 1 if the ith sample is of class k or zero otherwise



How to Start

- Start with single training sample
 - Check if output correct
 - Overfit I train accuracy should be 100%
 because input just memorized
- Increase to handful of samples
- Move from overfitting to more samples
 At some point, you should see generalization



How to Start

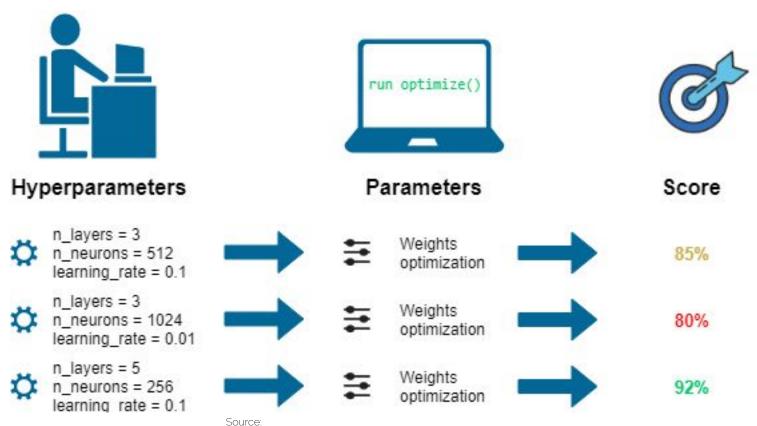


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Hyperparameters

- Network architecture (e.g., num layers, hidden layer, activation function)
- Number of iterations
- Learning rate(s) (i.e., solver parameters, decay, etc.)
- Regularization (more later next lecture)
- Batch size
- ...

Hyperparameter Tuning



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How to find good Hyperparameters?

- Manual Search (trial and error)
- Automated Search:
 - Grid Search
 - Random Search

```
from exercise_code.hyperparameter_tuning import grid_search
```

```
best_model, results = grid_search(
    dataloaders['train_small'], dataloaders['val_500files'],
    grid_search_spaces = {
        "learning_rate": [1e-2, 1e-3, 1e-4, 1e-5, 1e-6],
        "reg": [1e-4, 1e-5, 1e-6]
    },
    epochs=10, patience=5,
    model_class=ClassificationNet)
```

- Think about how different hyper parameters affect the model
 - E.g. Overfitting? -> Increase Regularization Strength, decrease model capacity

Exercise plan: Recap and Outlook

Exercise 03: Dataset and Dataloader Exercise 04: Solver and Linear Regression Exercise 05: Neural Networks Exercise 06: Hyperparameter Tuning

Numpy (Reinvent the wheel)

Exercise 07: Introduction to Pytorch Exercise 08: MNIST with Pytorch

Pytorch/Tensorboard

Exercise 09: Convolutional Neural Networks Exercise 10: Semantic Segmentation Exercise 11: Recurrent Neural Networks

Applications (Hands-off)

Summary

- Monday, June 16: Lecture 7 (*Training NN's 2*)
- Wednesday, June 18, 23:59:59: Deadline Ex6
 Pass it by achieving required accuracy on our hidden test set.
- Thursday, June 19: Tutorial Session 7 (Pytorch)



Good luck & see you next week ゔ